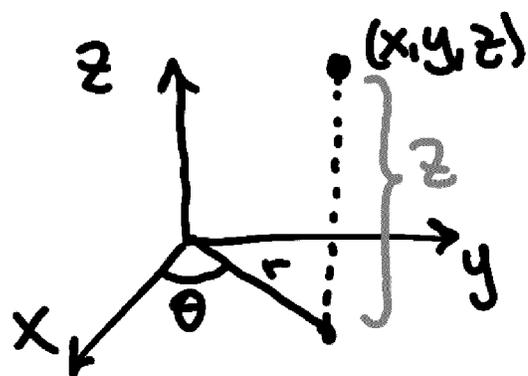
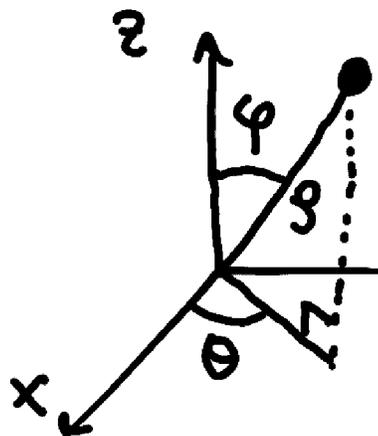


Recall: • Cylindrical coords  $(r, \theta, z)$



$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$

• Spherical coords  $(\rho, \theta, \varphi)$



$$\begin{cases} x = \rho \sin \varphi \cos \theta \\ y = \rho \sin \varphi \sin \theta \\ z = \rho \cos \varphi \end{cases}$$

$$\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$$

$$\bullet \lim_{t \rightarrow a} \vec{r}(t) = \left\langle \lim_{t \rightarrow a} x(t), \lim_{t \rightarrow a} y(t), \lim_{t \rightarrow a} z(t) \right\rangle$$

$$\bullet \vec{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle$$


---

Later, it will be convenient to normalize the tangent vector  $\vec{r}'(t)$  of a parametrized curve.

Define

$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}, \text{ provided}$$

that  $\|\vec{r}'(t)\| \neq 0$ .

It is called the "principal tangent vector."

## Integrals

Let  $\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$ . If

$x(t)$ ,  $y(t)$ , and  $z(t)$  are continuous functions over  $[a, b]$ , then

$$\int_a^b \vec{r}(t) dt = \left\langle \int_a^b x(t) dt, \int_a^b y(t) dt, \int_a^b z(t) dt \right\rangle$$

Also, this is of course true for indefinite integrals, too:

$$\int \vec{r}(t) dt = \left\langle \int x(t) dt, \int y(t) dt, \int z(t) dt \right\rangle$$

Ex:  $\vec{r}(t) = \langle 3t^2 + 2t, 3t - 6, 8t^3 \rangle$

$$\int \vec{r}(t) dt = \left\langle \int 3t^2 + 2t, \int 3t - 6 dt, \int 8t^3 dt \right\rangle$$

$$= \left\langle t^3 + t^2 + C_1, \frac{3t^2}{2} - 6t + C_2, 4t^4 + C_3 \right\rangle$$

Note: We need 3 different constant (one in each component).

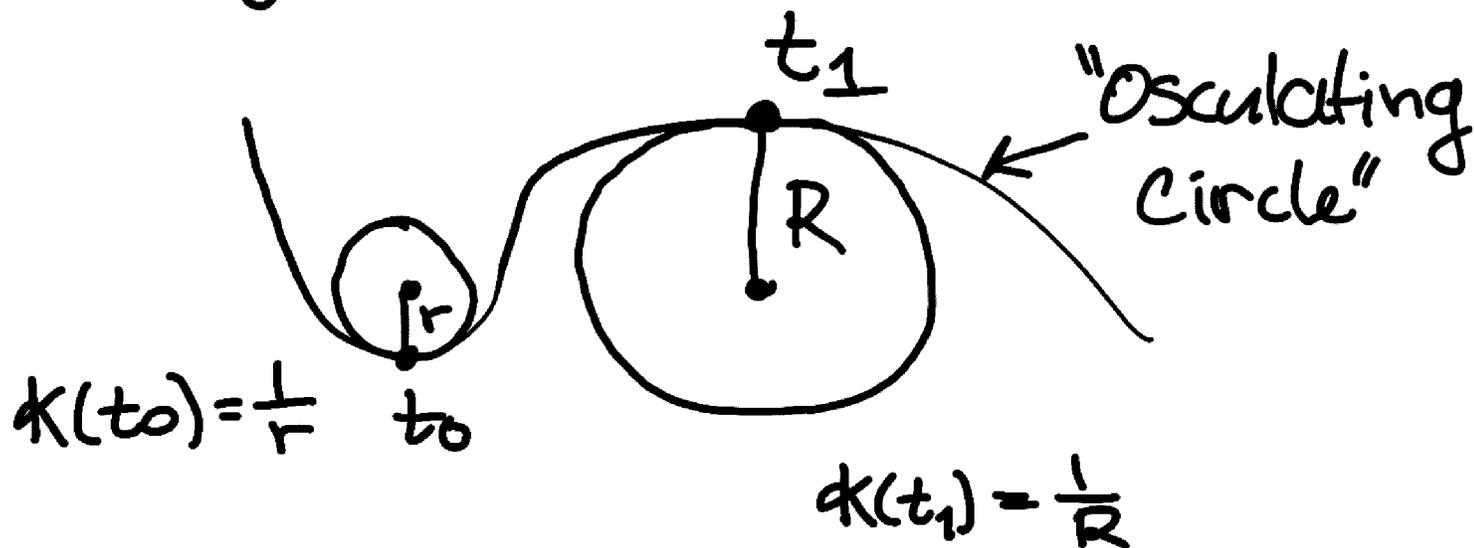
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### §3.3 Curvature

Definition If  $C$  is a smooth curve, its curvature at time  $t$  is

$$K(t) = \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|}$$

The curvature measures how sharply the curve "turns."



The radius of the so-called "osculating circle" is the reciprocal of the curvature.

---

Ex: Compute the curvature of

$$\vec{r}(t) = \langle \cos t, \sin t, t \rangle.$$

$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} = \frac{\langle -\sin t, \cos t, 1 \rangle}{\sqrt{2}}$$

$$\vec{T}'(t) = \left\langle -\frac{\cos t}{\sqrt{2}}, -\frac{\sin t}{\sqrt{2}}, 0 \right\rangle$$

$$\kappa(t) = \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|^2} = \frac{\sqrt{\frac{\cos^2 t}{2} + \frac{\sin^2 t}{2}}}{\sqrt{2}}$$

$$= \frac{\sqrt{1/2}}{\sqrt{2}} = \frac{1}{2}$$


---

The curvature can also be computed as

$$\kappa = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3} \cdot$$

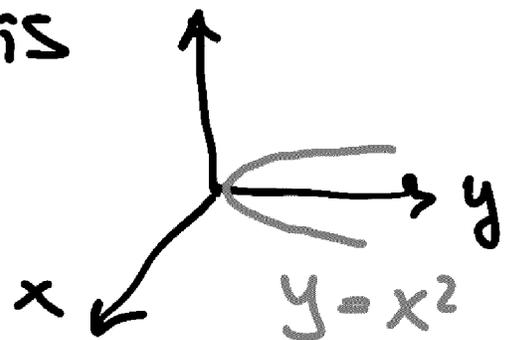
This is assuming that the curve belongs to space.

(Since the cross product only makes sense in space!)

If  $y = f(x)$ , a parametrization of its graph in space is

$$\vec{r}(t) = \langle t, f(t), 0 \rangle$$

It is contained



in the  $xy$ -plane, meaning  $z=0$ .

Now, let's compute the curvature:

$$\vec{r}'(t) = \langle 1, f'(t), 0 \rangle$$

$$\vec{r}''(t) = \langle 0, f''(t), 0 \rangle$$

$$\vec{r}'(t) \times \vec{r}''(t) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & f'(t) & 0 \\ 0 & f''(t) & 0 \end{vmatrix}$$

$$= \underbrace{\begin{vmatrix} f'(t) & 0 \\ f''(t) & 0 \end{vmatrix}}_{=0} \vec{i} - \underbrace{\begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix}}_{=0} \vec{j} + \begin{vmatrix} 1 & f'(t) \\ 0 & f''(t) \end{vmatrix} \vec{k}$$

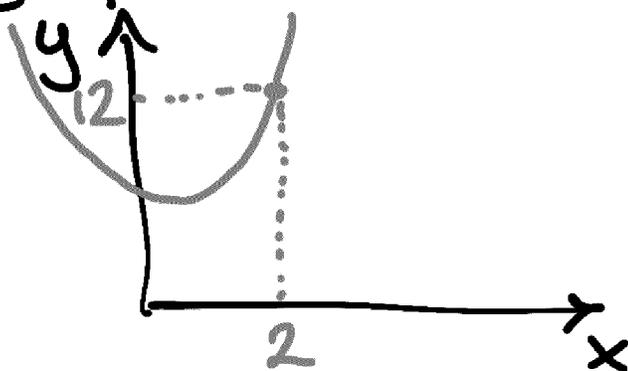
$$= f''(t) \vec{k} = \langle 0, 0, f''(t) \rangle.$$

$$\kappa = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3} = \frac{\|\langle 0, 0, f''(t) \rangle\|}{\|\langle 1, f'(t), 0 \rangle\|^3}$$

$$= \frac{|f''(t)|}{(1 + (f'(t))^2)^{3/2}}.$$

---

Ex: Let's find the curvature of the graph of  $f(x) = 3x^2 - 2x + 4$  at  $x=2$



$f'(x) = 6x - 2$ ,  $f''(x) = 6$ . Therefore, at  $x=2$  we have

$$k = \frac{|f''(2)|}{(1+(f'(2))^2)^{3/2}} = \frac{6}{(1+10^2)^{3/2}} = \frac{6}{(101)^{3/2}}$$
$$= \frac{6}{101\sqrt{101}} \approx 0.006$$

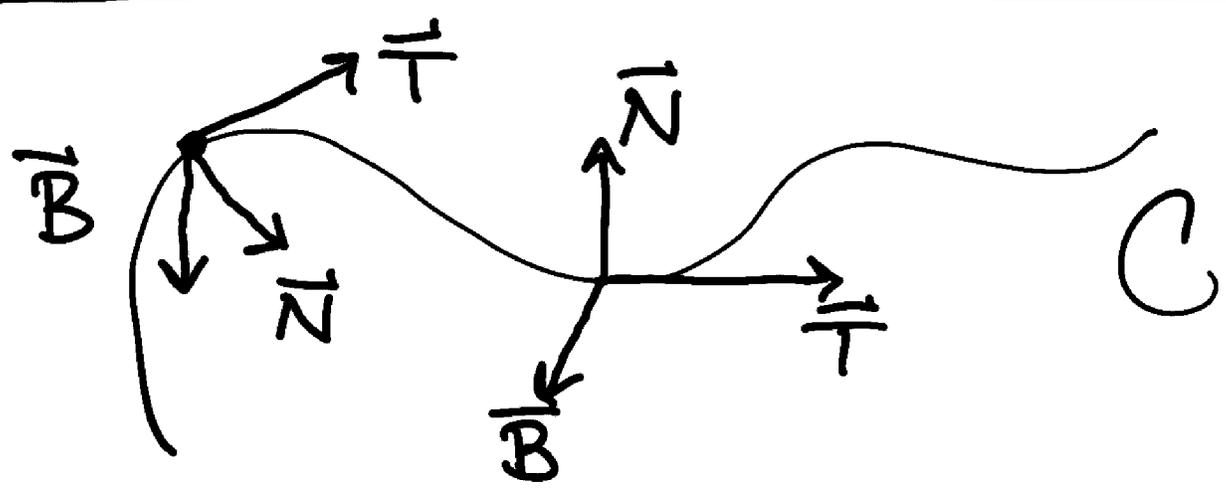
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Definition: If  $C$  is a smooth curve in space, and  $\vec{T}'(t) \neq 0$ , then the "principal unit normal vector" is

$$\vec{N}(t) = \frac{\vec{T}'(t)}{\|\vec{T}'(t)\|}$$

Definition: The "binormal vector"

is  $\vec{B}(t) = \vec{T}(t) \times \vec{N}(t)$ .



$\vec{r}(t)$  = position

$\vec{T}(t)$  = normalized velocity

$\vec{N}(t)$  = normalized acceleration